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Two-dimensional imaging of soot volume fraction in laminar diffusion flames

David R. Snelling, Kevin A. Thomson, Gregory J. Smallwood, and Ömer L. Gülder

A technique for acquiring two-dimensional soot-volume-fraction measurements in laminar flames has been demonstrated. The technique provides a map of very low noise concentration over a range of wavelengths (250–1100 nm). A noise level of 0.0007 in extinction and a spatial resolution of 30–40 μm for soot concentration were achieved with an arc lamp source that was filtered to provide greater spatial coherence and a CCD detector. The broadband arc lamp source also allowed us to avoid the added noise resulting from speckle with coherent laser sources. Beam steering, due to refractive-index gradients in the flame, was measured and compared with theoretical predictions. The optical arrangement to minimize the effect of beam steering is described. As a result the beam steering had no effect on the soot measurements in the flames examined. Flame-transmission maps obtained with this system in an ethylene/air laminar diffusion flame are presented. Tomographic analysis from use of an Abel inversion of the line-of-sight data to obtain radial profiles of soot concentration is described.

OCIS codes: 120.0120, 120.1740, 110.0110, 110.4280.

1. Introduction

In combustion research, measurements of soot volume fraction are important in studies of soot formation and radiation processes and for monitoring postflame particulates.¹ Light extinction is a commonly used diagnostic technique for measuring soot volume fraction. Although tomographic reconstruction from light extinction can be used to calculate soot profiles in radially symmetric laminar flames, this technique has the drawback of measuring a line-of-sight average that is not suitable for turbulent flame studies. Elastic scattering of light has been widely investigated for soot measurements, but the fact that the signal is proportional to the square of the particle diameter means that the technique is more useful for particle sizing than volume-fraction measurements. More important, for agglomerated soot particles (which are definitely not spherical), it has become increasingly clear in the last few years^{2,3} that the approach of applying Mie theory by assuming spherical soot particles results in large errors.

Laser-induced incandescence (LII) has emerged as a promising technique for measuring spatially and temporally resolved soot volume fraction in flames.^{4–9} In LII the soot is heated by a short-duration laser pulse to produce incandescence. With sufficiently high laser energies, numerical models of the heat transfer indicate that the soot particles reach temperatures of 4000–4500 K.^{5,6,10–12} The resultant radiation, which is blue shifted relative to soot radiation at normal flame temperatures and is of short duration, can readily be detected. LII typically has a temporal resolution of 10 ns and can be used to perform both point measurements and two-dimensional (2-D) planar visualization of soot. Numerical modeling of the LII signal indicates that, in appropriate conditions, the signal is approximately proportional to the soot volume fraction. However, LII does not presently provide absolute soot volume fractions and must be calibrated against other techniques.

To calibrate LII, and establish that the LII signal is linear with a soot volume fraction across a wide dynamic range, requires a calibration source whose soot volume fraction is known as accurately as possible. Laminar coflow diffusion flames, which are radially symmetric 2-D flames with good stability, provide such a source. The axial symmetry of these flames permits tomographic techniques to be used to obtain detailed maps of soot concentration. These techniques put additional demands on the precision of the line-of-sight data.

When this research was performed, all the authors were with the Combustion Group, Institute for Chemical Process and Environmental Technology, National Research Council of Canada, Building M-9, Ottawa, Ontario K1A 0R6, Canada. K. A. Thomson is now with the Department of Mechanical Engineering, University of Waterloo, Waterloo, Ontario N2L 3G1, Canada.

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In addition to LII calibration, accurate soot measurements are required for other projects. In fact much of the research on soot formation and oxidation has been conducted with a standard coflow laminar diffusion flame almost identical to the burner that we have used. The dependence of these soot fields on flame temperature, fuel type, and added diluents are an important source of information for understanding soot-formation mechanisms.¹

Most previous studies of soot have relied on sequential interrogation of the flame with narrow laser beams to provide spatial resolution.¹ Typical fractional noise levels (i.e., the observed sample standard deviation divided by the sample mean) of 0.005 in the transmission measurements have been achieved over the fairly lengthy scans that are necessary to map a flame. This achievement results in signal dynamic ranges of $\leq 50:1$ for the typical maximum attenuation (~ 0.25) found in these flames. In addition, the soot-concentration gradients in these flames are often high and flame movements or spatial reading errors of as little as $50\text{ }\mu\text{m}$ can be significant. Yet most research has been performed with laser beams with a spatial resolution of 1 mm or greater. With these problems in mind we have set out to design and build an optical system that would provide significantly more accurate line-of-sight attenuation 2-D maps of soot concentration in laminar flames. Greenberg and Ku¹³ have described a system that provides for monochromatic 2-D transmission measurements with noise levels approaching 0.0025 and acquisition rates of 30 Hz. Their system has worked well in mapping reduced-gravity diffusion flames where data-acquisition time is critical,¹⁴ but has a limited dynamic range. Our objective was to record images at very low noise levels in order to measure very low soot concentrations. This measurement required a light source that would avoid coherent effects. To achieve a dynamic range of better than 250:1 for a maximum attenuation of 0.25, the design goal was a fractional noise level of <0.001 in the transmission measurements with an image capture time of no more than a few seconds. The target radial spatial resolution was $50\text{ }\mu\text{m}$.

This performance is demonstrated with an arc lamp source that was filtered to provide greater spatial coherence, and a CCD detector. The arc lamp avoids the spectral coherence of laser sources and allows for a wide range of visible and near-IR wavelengths to be used. With sufficient soot-concentration levels, it is advantageous to perform concentration measurements with IR wavelengths. At these longer wavelengths the assumption that the soot particle radiation interaction is in the Rayleigh regime is more warranted. In addition, neglect of the scattering contribution to the extinction, which is commonly done in interpreting the results, is better justified at longer wavelengths.

The effect of beam steering in the flame was studied, and the optical arrangement to minimize the effect of this steering on the transmission maps is described. Flame-transmission maps obtained with this system in an ethylene/air laminar diffusion

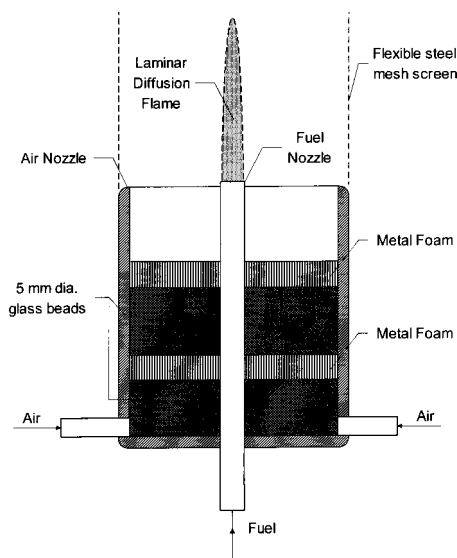


Fig. 1. Schematic diagram of the laminar diffusion flame assembly.

flame are presented. Tomographic analysis of the line-of-sight data by use of an Abel inversion technique, to obtain soot radial profiles is described.

2. Flame and Beam Steering

The laminar diffusion flame burner used in these studies is of a design similar to that previously used by us¹⁵ and other soot investigators^{1,3,7,11} and is shown in Fig. 1. The burner consists of a fuel tube with a 10.9-mm inner diameter, centered in an air nozzle 100-mm in diameter. Before exiting the nozzle the air passes through packed beds of glass beads and porous metal disks to prevent flame instabilities. The C_2H_4 fuel flow rate is $3.23 \times 10^{-6}\text{ m}^3/\text{s}$ (just under the smoke-point fuel flow rate), and the air flow is $4.73 \times 10^{-3}\text{ m}^3/\text{s}$. The C_2H_4 used is research grade (99.99% pure) and supplied by Matheson. Air is provided from an in-house compressor and filtered. A flame enclosure made of flexible steel mesh protects the flame from air movements in the room while appropriate holes provide optical access. The burner assembly is attached to a positioning platform with accurate and repeatable vertical and horizontal movement capability.

The spatial integrity of 2-D soot attenuation images can potentially be compromised by beam steering due to refractive-index gradients. To measure this beam steering, a He-Ne laser beam traversed the flame and was incident on a Beam View imaging system equipped with a Cohu 4800 camera. The 543.5-nm He-Ne laser beam had a Gaussian diameter ($1/e^2$) of 0.8 mm. The flame-to-camera distance was 1.5 m. The position of the undeflected laser beam was recorded in the absence of the burner. With the burner in place the beam displacement was measured as a function of the radial position of the laser beam relative to the burner center. The Beam View software recorded the centroid of the laser beam intensity profile. The results of these experiments

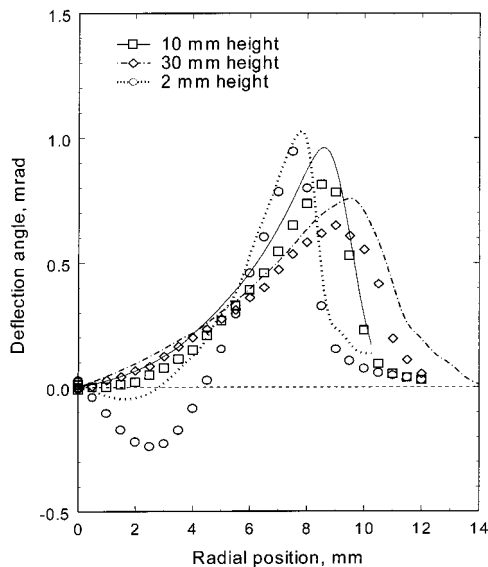


Fig. 2. Experimental observations (symbols) and theoretical predictions (curves) of beam steering in laminar diffusion flame.

are shown in Fig. 2 for three different heights in the burner.

The laser deflection angle θ_r in the flame is described by¹⁶

$$\theta_r = - \int_0^z \left(\frac{1}{n} \right) \left(\frac{\partial n}{\partial r} \right) dz \approx - \int_0^z \frac{\partial \delta}{\partial r} dz, \quad (1)$$

where $n = 1 + \delta$ is the refractive index and z is the coordinate along the beam. In flames, δ is generally small (<0.0003), and the approximation in Eq. (1) is accurate. We have used the coherent anti-Stokes Raman spectroscopy (CARS) technique to measure temperature profiles in this flame,¹⁷ and these profiles, shown in Fig. 3, have been used to calculate the theoretical beam deflection with Eq. (1). In the absence of detailed composition information we have neglected the combustion products and assumed the gas to be dry air. By doing this we underestimate the refractive index. However, the major variation comes from the temperature gradient. The error in this assumption will be small to the air side of the reaction zone where the major species is nitrogen and, as we will show, where the beam steering is greatest. The CARS temperature data were fitted to a curve by using the loess function in MathCad, and the refractive index at 570 nm was calculated from $\delta = 0.00027 [288/T(r)]$,¹⁸ where 288 is the reference temperature in degrees Kelvin and $T(r)$ is the flame temperature in degrees Kelvin as a function of radial position. The constant term in the expression for the δ value is a weak function of wavelength varying from 0.000291 at 300 nm to 0.000274 at 1000 nm. Results of the numerical integration of Eq. (1) over the flame path are shown in Fig. 2 where the deviation is calculated in the radial (horizontal) direction. There were much smaller observed deflections in the

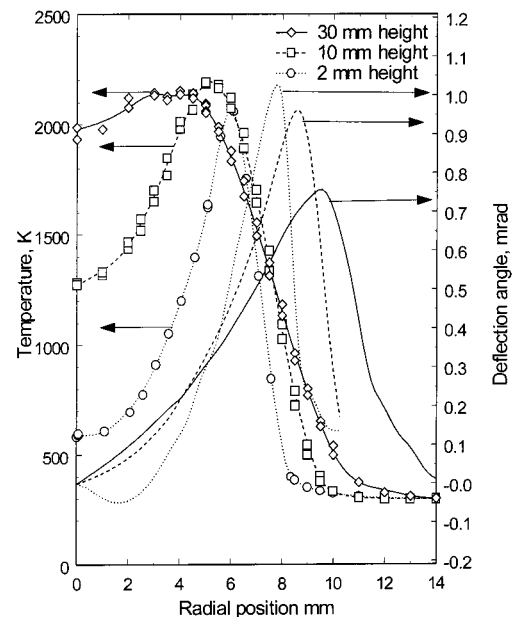


Fig. 3. Theoretical beam steering and CARS temperature profiles in laminar diffusion flame.

vertical direction that result from the much lower temperature gradients in this direction.

The calculated beam deflection is typically 10–25% greater than the observed values, as shown in Fig. 2. Given the approximations involved in the model, this agreement is satisfactory and the model correctly predicts the radial location of the maximum deflection. At the 2-mm height, close to the burner center, the agreement is much poorer and the calculated value greatly underestimates the observed deflections. This underestimation is not surprising since at these low heights the gas at the burner centerline is almost pure ethylene (which has a refractive index ~ 2.2 times higher than that of air), and diffusion results in a greater admixture of air and/or combustion products as the flame front is approached. Thus at a 2-mm height in the burner the refractive index decreases with increasing radial position both because of increases in temperature and because of increasing dilution of the ethylene with air. In these circumstances the model substantially underpredicts the beam deflection.

The predicted beam deflection and CARS flame temperatures are shown in Fig. 3. With increasing height in the flame the visible sooting region of the flame narrows, as indicated by the reducing radial location of the maximum temperature point. However, the diameter of the visible flame increases with height, as the combustion products diffuse outward. An examination of Fig. 3 shows that the radial location of the maximum beam steering also increases with height. The maximum beam steering at each height is located in the 500–770-K temperature range. This behavior is to be expected since the refractive-index gradients scale approximately as $(1/$

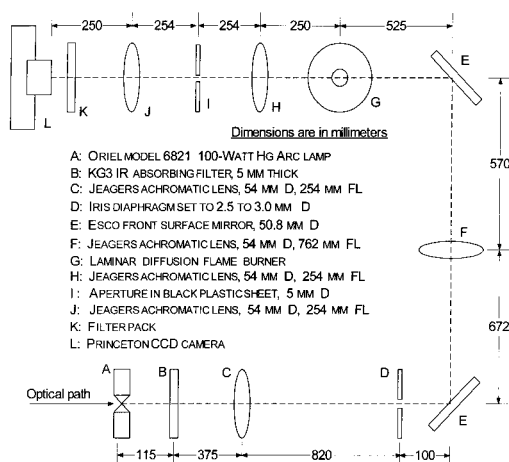


Fig. 4. Optical layout for 2-D soot-transmission measurements.

$T^2)dT/dr$, and the low-temperature regions of the flame thus dominate the beam steering.

These beam deflections will compromise the spatial integrity of 2-D soot measurements in that flame images will be displaced from reference images taken in the absence of the flame. In fact, if illuminated by a collimated light beam, the flame will produce a shadowgraph image¹⁶ where the intensity variations result from the spatial gradient of the beam deflections. Imaging the source of the beam disturbance on the detector image plane can minimize the shadowgraph effect. A residual shadowgraph image remains whose effect varies with the ratio of the length of the source (the flame in our case) to the focal length of the imaging lens. Howes and Buchelle¹⁹ show that if the refractive-index gradient is a linear function of distance, the image is distortionless provided that the center of the test section (the flame in our case) is imaged at the detector surface. A 2-D soot optical system incorporating virtually distortionless imaging is described below. This system is also the optical arrangement selected by Greenberg and Ku.¹³

3. Two-Dimensional Soot Attenuation Optics

The optical layout of the soot-imaging experiments is shown in Fig. 4. The arc of the Hg lamp is focused on an aperture with a 3.0-mm diameter with an achromatic lens with a 254-mm focal length. The light passing through this aperture is then collimated with lens F and is incident on the flame. The postflame optics consist of two further 254-mm achromats (H and J) the first of which focuses the light onto aperture J and the second of which recollimates the light. As noted by Greenberg and Ku¹³ this arrangement provides a telecentric imaging system with constant magnification (1.0 in this case). The CCD camera position is such that the center of the flame and the detector plane are optically conjugate to minimize the effects of beam steering in the flame.

The spatial filtering of the light source sets a limit on the resolution attainable in the flame. The full angle divergence of the effective light source is <3.4

mrad, which provides a maximum resolution of $0.0034d_f/M$ in the flame, where d_f is the diameter of the sooting part of the flame and M is the magnification. For our setup $M = 1$ and $d_f < 10$ mm so that the resolution in the flame and at the detector is better than $34 \mu\text{m}$, which is ~ 1.5 camera pixels. The detector is a Princeton Instruments CCD Model EEV-TE-1152 \times 1242 with a Model ST138 controller. The detector array size is 1152×1242 pixels with a square pixel size of $22.4 \mu\text{m}$.

Aperture J in Fig. 4 greatly reduces the flame radiation reaching the detector. Aperture J is sufficiently large to avoid schlieren effects resulting from beam steering in the flame. The operating wavelength is selected by the choice of the interference filter, which is part of the filter pack in front of the CCD. A 20-nm bandwidth filter centered at 577 nm was used in these experiments. Two neutral-density filters whose combined transmission was 0.0016 were added to reduce flame radiation. The maximum signal from the flame alone was approximately 200 counts (from the region of the highest-temperature soot) compared with the typical lamp signal of 30,000 counts. This background was subtracted from lamp-plus-flame exposure to give the lamp-only signal. This flame signal, while negligible, can be further reduced by decreasing the diameter of aperture I (Fig. 4), which is larger than needed to avoid schlieren effects. We also compared the flame radiation to the lamp intensity at 825 nm. At 825 nm the maximum flame radiation was 500 counts and the lamp signal 30,000 counts with an aperture, I, size of 2.5 mm.

The objective of <0.001 noise in the transmission measurements dictates that the fractional shot noise in the flame images be lower than 0.001. The target fractional shot noise is 0.0003 and requires a signal of $>1/0.0003^2$ photoelectrons or $\sim 10^6$ counts [for our detector sensitivity of ~ 10 photoelectrons/analog-to-digital-converter (ADC) count]. In practice we have summed a 25-pixel region in the vertical direction, giving a spatial resolution of $\sim 500 \mu\text{m}$ in that direction, which improves the signal-to-noise over that of a single pixel by $\sim 25^{0.5}$ or ~ 5 . Thus a single-pixel signal level of 200,000 counts or greater is sufficient to render the detector shot noise insignificant. Since the ADC of our CCD is limited to 64,000 counts, five sequential images were acquired and summed to provide the required final image signal-to-noise ratio.

To account for potential intensity drifts in the lamp, we recorded reference images (I_o) both before and after the flame image I . If the intensity varied linearly with time, an average of these two references would provide an accurate image to ratio the flame image to. Observation of regions of the image well beyond the flame shows that in practice there were often small residual differences between the I and averaged I_o images. A statistical analysis of sequential images showed that the distribution of intensities within an image (the standard deviation of the individual pixel values) was much more repeatable than the total image-to-image intensity. The repeatability

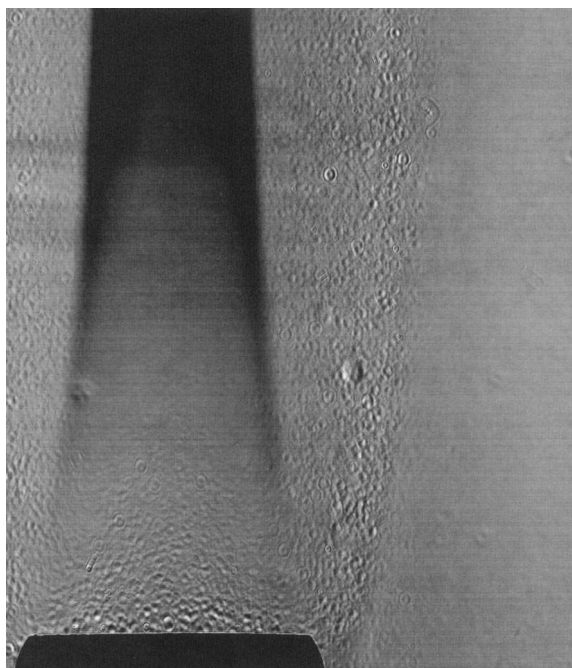


Fig. 5. Image of sooting flame ratioed to the reference image recorded in the absence of the flame.

ity was better after the lamp had warmed up for 60 min, when the standard deviation of a ratioed image had fallen to that expected from the shot noise limit of the individual images. The ratio image I/I_0 was divided into strips of 500- μm height taken at height intervals of 2 mm. As a result of the above statistical observation we performed a secondary normalization, using the area of the image well to one side of the flame, where full transmission would be expected, which was normalized to 1.0.

A typical ratio image of the flame is shown in Fig. 5. The weak attenuation by soot can be faintly seen and the tip of the burner is clearly visible. The circular structures observable in the ratio image are also present in the I and I_0 images. However, unlike the individual images, these structures disappear, or become much less prominent, in certain regions of the ratio images. A comparison of Figs. 2 and 5 (using the burner tip dimensions to set the scale in Fig. 5) establishes that these blemishes are most prominent in the region of maximum beam steering and disappear in regions of the flame where there is little beam steering. The circular defects in the individual images appear to be due to diffraction effects arising from scattering by surface defects and dust on the optics. A detailed examination of the structures in the ratio image indicates that these blemishes appear to result from the effect of ratioing two diffraction patterns that are slightly displaced in the horizontal direction producing a slightly oval image with alternating light and dark bands. Thus the appearance of these diffraction phenomena in the ratio image are indicative of the effect of beam steering in the flame that is only partially compensated for by ensuring

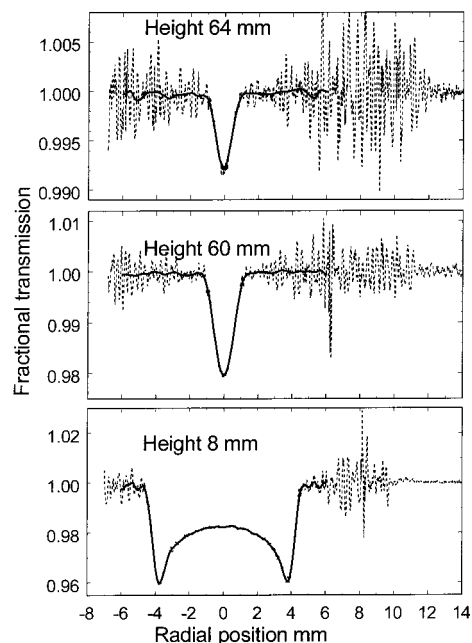


Fig. 6. Three strips of the transmittance of a $\text{C}_2\text{H}_4/\text{air}$ diffusion flame taken from a 2-D image showing the original data and the MathCad loess smooth of the data.

that the burner center and the CCD detector are optically conjugate.

Figure 6 shows the intensity profile of three of the strips taken from low-extinction regions of a flame image along with a MathCad loess smooth fit to the data, which represents the intensity in the superpixel (25 vertically by one horizontally). This image has been normalized as outlined above by using the noise-free region beyond the flame boundary (beyond 12 mm radially at a height of 8 mm). A single normalization factor is used for each image. The regions in which the noise is high are clearly coincident with the appearance of structures in the ratio image and correspond to regions of maximum beam steering. Both Figs. 5 and 6 show that the noise is low in the region of soot absorption. We routinely perform statistical analysis on the baseline data of each of the strips. The noisy and noise-free regions were analyzed separately to give the mean, the standard deviation, and the standard deviation of the mean for each of the strips. (The standard deviation is the noise of a superpixel.) A typical sample is shown in Table 1 where one can see that the mean intensity in the ratioed image is not only constant for each strip but also the same in both of the regions analyzed. The noise (single standard deviation) in the signal is typically 0.0004 in the region beyond the flame and 0.007 in the region of maximum beam steering. The standard deviation of the means is typically a factor of 10 less than 0.007 since approximately 100 pixels were averaged in each region. From Table 1 it can be seen that, in the region of maximum beam steering, the mean intensity is 1.0 with an uncertainty of 0.0007, indicating that there is no absorption in this

Table 1. Statistics of Noise-Free and Noisy Regions^a

Height (mm)	Image Region well beyond Flame			Image Region of Maximum Beam Steering		
	σ	Mean	σ_{mean}	σ	Mean	σ_{mean}
2	0.000456	0.99810	0.000045	0.007065	0.99951	0.000707
4	0.000371	0.99904	0.000037	0.006834	1.00004	0.000683
6	0.000339	0.99957	0.000033	0.008852	1.00091	0.000885
8	0.000314	0.99987	0.000031	0.005154	1.0002	0.000515
10	0.000390	1.00009	0.000039	0.003343	1.00022	0.000334
12	0.000433	1.00009	0.000043	0.006267	0.99993	0.000626
14	0.000304	1.00016	0.000030	0.007864	1.00083	0.000786
16	0.000288	1.00002	0.000029	0.007369	1.00052	0.000736
18	0.000280	1.00008	0.000028	0.008964	1.00028	0.000896
20	0.000330	1.00012	0.000033	0.006416	1.00071	0.000642

^a σ , standard deviation

region. This analysis was carried out for each image, and the routine transmission measurements were established to a precision of much less than the required 0.001. The single-pixel noise in the sooting region of the flame is expected to be close to that of the noise-free region of the image (0.0004), since beam-steering effects are small there. For the Abel inversion, to be discussed in Section 4, it was found that the maximum resolution was attained for an inversion step size of $\sim 100 \mu\text{m}$ (4 pixels). The observed transmissions were therefore smoothed by using the loess function to obtain a final resolution of $100 \mu\text{m}$. This 4-superpixel average will result in a further factor of 2 reduction in the single-superpixel noise values of Table 1. The averaged intensity of the before and after reference image was typically within 0.005 of the flame image in the region beyond the flame. The constancy of the means in the ratio image to <0.001 with changing location supports the earlier observation that the spatial distribution of intensity within the image is more stable than the absolute intensity.

4. Abel Inversion Algorithm

The one-dimensional tomography is performed with a three-point Abel inversion method. The algorithm used is that of Dasch²⁰ who compared Abel, onion-peeling, and filtered backprojection methods and found the three-point Abel method to be the best because of its low noise, robustness, and speed.

For particles in the Rayleigh limit, $(\pi d/\lambda) < 0.3$, the soot volume fraction f_v is given by

$$f_v = \frac{\ln(\tau)\lambda}{6\pi LE(m)}, \quad (2)$$

where τ is the transmission, λ the wavelength, L the path length, and $E(m) = -\text{Im}[(m^2 - 1)/(m^2 + 2)]$; m is the complex refractive index of soot, $m = k + ni$. Equation (2) can be written in its differential form as

$$\frac{d \ln(\tau)}{dr} \left[\frac{\lambda}{6\pi LE(m)} \right] = f_v(r). \quad (3)$$

Each strip of the 2-D transmission measurements provides experimental values of τ versus r , the displacement from burner center. The Abel inversion of these data returns the quantity $d \ln(\tau)/dr$ versus r , which, when Eq. (3) is used, can be converted to radial profiles of the soot volume fraction. Using the dispersion relationship from Dalzell and Sarofim²¹ to calculate the refractive index of soot at 577 nm, we obtain $m = 1.59 + 0.566i$ and $E(m) = 0.258$.

Dasch²⁰ has shown that the noise (expressed as a ratio of the noise in the inversion to noise in the chordal projections) in the inversion is inversely proportional to the spacing between the data [$\ln(\tau)$ values]. We have found that data spacing of $100 \mu\text{m}$ provides the optimum resolution. Any further decrease in step size increased the inversion noise without adding further definition to the soot profiles, even in the regions of maximum soot gradients. The center of the transmission curves was located first by smoothing the data and then, starting from the two edges of the flame, by finding the pixel values for which the intensity was 2/3 of the maximum value. We then averaged the left- and right-hand values to locate the center of the transmission curves. The precision of this algorithm in locating a burner center was greatly increased by the low noise in the data. Figure 7 shows Abel inverted data in flame regions of low soot extinction, which is the worst-case outcome. It can be seen from Figs. 6 and 7 that peak absorption of as little as 1% provides sufficient signal-to-noise for the inversion.

Figure 8 is a typical example of the inverted transmission data in a region of high soot concentration. The excellent agreement between the two halves of the inversion is attributable to the symmetry of the flame and the absence of noise in the transmission measurements.

If we assume a spacing of 0.1 mm and a maximum noise of 0.0005 in the τ value of the 25×4 superpixel [and hence $\ln(\tau)$ values] projections, the theoretical noise in the Abel inversion [$d \ln(\tau)/dr$], when the data from Dasch²⁰, are used, is 0.003 on the burner center, decreasing monotonically to 0.0003 at $r = 2.0 \text{ mm}$.²⁰ When converted to soot concentration, these noise values imply an uncertainty in the soot concentration

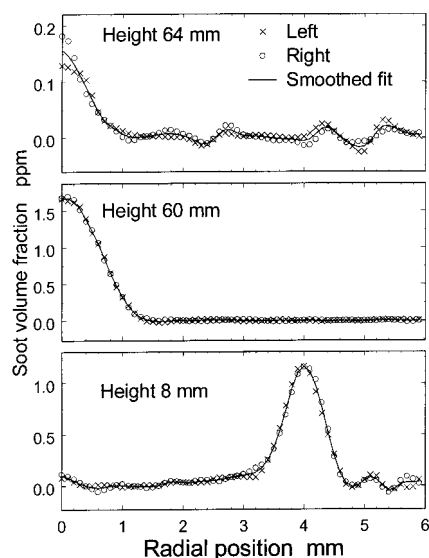


Fig. 7. Abel inversion of the transmittance curves of Fig. 6 showing the soot volume fraction determined from the right- and left-hand side of the image and a smoothed fit of both data sets.

of 0.35, 0.075, and 0.035 for $r = 0, 0.5$, and 2.0 mm, respectively. This theoretical noise behavior assumes that the rms noise is constant independent of the projection. From the discussion of beam-steering effects it is clear that this assumption is not true. In these experiments the noise is a minimum on the centerline and increases as the projections approach the region of maximum beam steering. However, the theoretical values are consistent with the data in Figs. 6 and 7, which show that the noise is observable at the burner center but falls rapidly

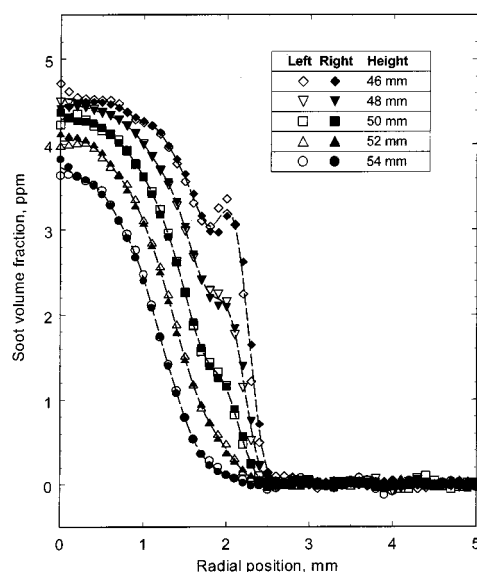


Fig. 8. Abel inversion of the transmittance curves taken in the region of moderate soot concentration of the C_2H_4 /air diffusion flame showing the soot volume fraction determined from the right- and left-hand side of the image and a smoothed fit (broken lines) of both data sets.

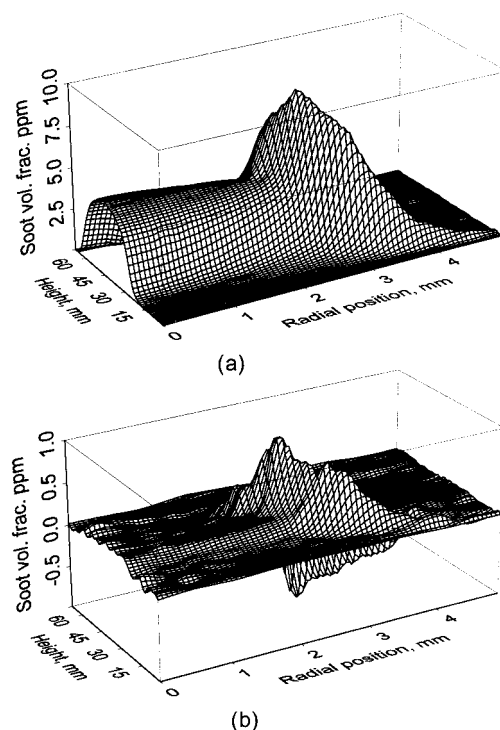


Fig. 9. Three-dimensional map of soot concentration in the C_2H_4 /air diffusion flame showing (a) a complete flame data set and (b) the difference between data sets taken on different days.

with increasing r . The asymptotic noise estimate of ~ 0.04 ppm for $r \geq 2.0$ is consistent with our observations, but the centerline prediction of 0.4 ppm overestimates the observed error, probably for the reasons noted above. Since the noise in the inversion is inversely proportional to the projection spacing, a projection spacing of 0.2 mm could lower the noise a factor of 2 with minimal loss of resolution in most parts of the flame.

5. Soot-Concentration Maps

The soot concentration in the C_2H_4 /air flame was mapped with three separate images to cover the ~ 70 -mm height of the flame. A complete flame measurement of soot concentration is shown in Fig. 9(a), where we have shown one half of the symmetric flame. In Fig. 9(b) the difference between two soot-concentration maps taken on different days is shown. This plot shows a systematic difference between the flames recorded on different days. A detailed examination of the data for the two flames showed that the flame height of one flame was approximately 1.0–1.5% larger. This slightly larger flame had approximately 2.5% more total soot and the location of its maximum soot contour was consistently at a radial position 30–40 μm greater in the 25–40-mm-height region (where the differences are maximum). Observation of such a minor change in flame diameter provides a measure of the effective spatial resolution. Since the Abel inversion was performed at a 100- μm spacing, the position of the maximum soot contour at the selected heights was obtained by curve fitting the

data. These differences, which were consistent across the multiple images necessary to measure a complete flame, attest to the low noise and repeatability of the data on a given day. In these laminar diffusion flames the flame width is expected to be proportional to the height,²² and the small differences observed are consistent with this. These small variations in flame profiles may result from daily atmospheric pressure changes.

6. Conclusions

We have demonstrated a technique for acquiring 2-D maps of flames that provide very low noise. Two-dimensional attenuation measurements at 577 nm are presented, and the lamp is shown to have sufficient intensity to overcome flame radiation at 825 nm. Extension to wavelengths shorter than 577 is straightforward since flame radiation drops dramatically whereas lamp intensity decreases more slowly with decreasing wavelength. The technique has the potential to cover wavelengths from 250 to 1100 nm (the limit of the silicon detector). A noise level of 0.0007 in extinction and a spatial resolution of 30–40 μm for soot concentration were attained. The broadband arc lamp source also allowed us to avoid added noise resulting from speckle with coherent laser sources. Beam steering, due to refractive-index gradients, was measured and compared with theoretical predictions. The effect of beam steering was minimized through careful optical arrangement and had no effect on the soot measurements in the flames examined. In addition to substantially improved sensitivity and spatial resolution, the 2-D technique provides a significant time saving over point measurements of transmission.

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